

VNU-HUS MAT1206E/3508: Introduction to AI

Reasoning with Uncertainty

In-class Discussion

Hoàng Anh Đức

Bộ môn Tin học, Khoa Toán-Cơ-Tin học
Đại học KHTN, ĐHQG Hà Nội
hoanganhduc@hus.edu.vn



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Definition

- **Sample space Ω** : the finite set of *all possible outcomes* for an experiment.
- **Event**: subset of Ω .
 - If the outcome of an experiment is included in an event E , then event E has occurred.
 - A and B are events $\Rightarrow A \cup B$ is an event.
- **Elementary event**: subset of Ω containing exactly one element.
- **Sure event**: Ω .
- **Impossible event**: $\emptyset$.

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Laplace Probability

Let $\Omega = \{\omega_1, \dots, \omega_n\}$ be finite, and assume that its outcomes are *equally likely* (the *Laplace assumption*). Under this assumption, define, for every event $A \subseteq \Omega$,

$$P(A) := \frac{|A|}{|\Omega|} = \frac{\text{number of outcomes in } A}{\text{number of possible outcomes}}.$$

Example 1

For a fair die, the probability of an even number is

$$P(\text{face_number} \in \{2, 4, 6\}) = \frac{|\{2, 4, 6\}|}{|\{1, 2, 3, 4, 5, 6\}|} = \frac{3}{6} = \frac{1}{2}.$$

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Quiz: Choosing the Sample Space



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Quiz

Two fair dice are rolled. Let S be the sum of their results. A student applies the Laplace formula to the possible values $\{2, 3, \dots, 12\}$ and concludes that $P(S = 7) = 1/11$. Which statement is correct?

- (a) The conclusion is correct because S has 11 possible values.
- (b) The conclusion is incorrect because the possible values of S are not equally likely.
- (c) The conclusion is incorrect because the Laplace formula applies only to elementary events.

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Definition

For events A and B with $P(B) > 0$, define the *conditional probability* of A given B by

$$P(A \mid B) := \frac{P(A \wedge B)}{P(B)}.$$

If $P(B) = 0$, elementary conditional probability is *undefined*.

Under the *Laplace assumption*, this can also be written as

$$P(A \mid B) = \frac{|A \wedge B|}{|B|}.$$

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Definition

If $P(B) > 0$, events A and B are called *independent* if

$$P(A \mid B) = P(A).$$

If $P(B) = 0$, we define B to be independent of every event.

Theorem 1

For independent events A and B , $P(A \wedge B) = P(A)P(B)$.

■ *Product Rule:*

$$\mathbf{P}(A, B) = \mathbf{P}(A \mid B)\mathbf{P}(B)$$

■ *Chain Rule:* (Obtained by repeatedly applying the product rule.)

$$\mathbf{P}(X_1, \dots, X_n) = \prod_{i=1}^n \mathbf{P}(X_i \mid X_1, \dots, X_{i-1}).$$

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Quiz: Dependence versus Causation



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Quiz

Let A and B be events with $P(A) > 0$. Suppose that

$$P(B \mid A) > P(B).$$

Which conclusion must be true?

- (a) A causes B .
- (b) B causes A .
- (c) A and B are not independent.

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Quiz: A Probability-Zero Event



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Quiz

Let A be any event, and suppose that $P(B) = 0$. Which statement matches the definition used in this lecture?

- (a) $P(A | B) = P(A)$, so A and B are independent.
- (b) $P(A | B)$ is undefined, but A and B are independent.
- (c) $P(A | B)$ is undefined, so A and B are dependent.

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Example 2 (Simplified Alarm Model)

Al The alarm sounds.

Bur A burglary occurs.

$P(Bur, Al)$	<i>Bur</i>	$\neg Bur$	Total
<i>Al</i>	0.0099	0.0990	0.1089
$\neg Al$	0.0001	0.8910	0.8911
Total	0.0100	0.9900	1

For example, it holds:

$$\begin{aligned}P(Al) &= P(Al, Bur) + P(Al, \neg Bur) \\&= 0.0099 + 0.0990 = 0.1089,\end{aligned}$$

$$P(Al \mid Bur) = \frac{P(Al, Bur)}{P(Bur)} = \frac{0.0099}{0.0100} = 0.99.$$

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Theorem 2 (Bayes' Theorem)

$$P(A \mid B) = \frac{P(B \mid A)P(A)}{P(B)}.$$

Example 2 (continued)

$$\begin{aligned} P(Bur \mid Al) &= \frac{P(Al \mid Bur)P(Bur)}{P(Al)} = \frac{0.99 \cdot 0.0100}{0.1089} \\ &= \frac{0.0099}{0.1089} \approx 0.0909. \end{aligned}$$

- $P(Al \mid Bur)$: known burglary $\rightarrow$ chance that the alarm sounds; the alarm's *sensitivity*.
- $P(Bur \mid Al)$: known alarm $\rightarrow$ chance of a burglary; *depends on the local burglary rate and false alarms*.
- Here 0.0099 is the (Al, Bur) cell, while 0.1089 is the Al row total.

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Quiz: The Effect of the Base Rate



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Quiz

The same alarm system is used in two areas. For each $i \in \{1, 2\}$, $P_i(Al | Bur) = 0.99$ and $P_i(Al | \neg Bur) = 0.10$. However, $P_1(Bur) = 0.01$ and $P_2(Bur) = 0.001$. Consider the probability of burglary given an alarm, $P_i(Bur | Al)$. Which statement is correct?

- (a) It is the same in both areas.
- (b) It is higher in Area 1.
- (c) The alarm is less sensitive in Area 2.



The Principle of Maximum Entropy

Let X be a discrete random variable with possible values $x_1, x_2, \dots, x_n$ and probability distribution $\mathbf{P}(X) = (p_1, p_2, \dots, p_n)$, where $p_i = P(X = x_i)$.

Definition

The *(information) entropy* H of the distribution $\mathbf{P}(X)$ is defined as $H(\mathbf{P}) = -\sum_{i=1}^n p_i \log p_i$ (with the convention $0 \log 0 := 0$).

- Entropy is a *measure of the uncertainty* associated with a random variable.
 - The *higher the entropy*, the *more uncertain or unpredictable the variable* is.
 - If one outcome has probability 1 and all others 0, then the entropy is 0 (no uncertainty).
 - If all outcomes are equally likely, then the entropy is maximized (maximum uncertainty).
- The *maximum-entropy principle (MaxEnt)* selects, among all distributions satisfying the stated constraints, a distribution that maximizes H [Ertel 2025], p. 141.

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■ Distribution

$$\mathbf{P}(A, B) = (P(A, B), P(A, \neg B), P(\neg A, B), P(\neg A, \neg B))$$

■ Abbreviation

$$p_1 = P(A, B)$$

$$p_2 = P(A, \neg B)$$

$$p_3 = P(\neg A, B)$$

$$p_4 = P(\neg A, \neg B)$$

- These four parameters (unknowns) $p_1, \dots, p_4$ define the distribution.
- Out of it, any probability for A and B can be calculated.
- Four equations are required to calculate these unknowns.

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- Normalization condition: $p_1 + p_2 + p_3 + p_4 = 1$.
- From the given values $P(A) = \alpha$ and $P(B | A) = \beta$ we calculate

$$P(A, B) = P(B | A) \cdot P(A) = \alpha\beta$$

$$P(A) = P(A, B) + P(A, \neg B).$$

- So far, we have the following system of three equations

$$p_1 + p_2 + p_3 + p_4 = 1$$

$$p_1 = \alpha\beta$$

$$p_1 + p_2 = \alpha$$

- Solve it as far as is possible, we get

$$p_1 = \alpha\beta$$

$$p_2 = \alpha(1 - \beta)$$

$$p_3 + p_4 = 1 - \alpha$$

One equation is missing!

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- To come to a definite solution despite this missing knowledge, we change our point of view. **We use the given equations as constraints for an optimization problem.**
- The full joint distribution is still

$$\mathbf{p} = (p_1, p_2, p_3, p_4),$$

with $p_1 = \alpha\beta$ and $p_2 = \alpha(1 - \beta)$ already fixed, and free variables $p_3, p_4 \geq 0$ under $p_3 + p_4 = 1 - \alpha$.

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- The *full entropy* is

$$H(\mathbf{p}) = - \sum_{i=1}^4 p_i \ln p_i = -p_1 \ln p_1 - p_2 \ln p_2 - p_3 \ln p_3 - p_4 \ln p_4.$$

- Define the free part

$$H_{\text{free}}(p_3, p_4) := -p_3 \ln p_3 - p_4 \ln p_4.$$

Then $H(\mathbf{p}) = H_{\text{free}}(p_3, p_4) + C$, where the constant $C = -p_1 \ln p_1 - p_2 \ln p_2$ does *not* depend on p_3, p_4 .

- Therefore maximizing $H(\mathbf{p})$ over p_3, p_4 is the same as maximizing $H_{\text{free}}(p_3, p_4)$ under $p_3 + p_4 = 1 - \alpha$.

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- **Problem:** Maximizing $H_{\text{free}}(p_3, p_4) = -p_3 \ln p_3 - p_4 \ln p_4$ subject to $p_3 + p_4 - 1 + \alpha = 0$.

- Lagrange function:

$$\begin{aligned} L &= H_{\text{free}}(p_3, p_4) + \lambda(p_3 + p_4 - 1 + \alpha) \\ &= -p_3 \ln p_3 - p_4 \ln p_4 + \lambda(p_3 + p_4 - 1 + \alpha) \end{aligned}$$

- Taking the partial derivatives with respect to p_3 and p_4

$$\frac{\partial L}{\partial p_3} = -\ln p_3 - 1 + \lambda = 0, \quad \frac{\partial L}{\partial p_4} = -\ln p_4 - 1 + \lambda = 0.$$

- These two equations along with the constraint give us a system of three equations and three unknowns p_3, p_4, λ . Solving it, we have $p_3 = p_4 = (1 - \alpha)/2$. Evaluating H_{free} gives $(1 - \alpha)(\ln 2 - \ln(1 - \alpha))$ at this solution and $-(1 - \alpha) \ln(1 - \alpha)$ at the boundary points $(0, 1 - \alpha)$ and $(1 - \alpha, 0)$. The first is larger by $(1 - \alpha) \ln 2$, so this is the *maximum*.

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Quiz: Completing Missing Probabilities



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Quiz

Suppose $P(A) = 0.4$ and $P(B \mid A) = 0.75$. Under the MaxEnt solution above, what is $P(B \mid \neg A)$?

- (a) 0.30
- (b) 0.50
- (c) 0.75

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- No knowledge is given, so no world is distinguished from the others.
- No constraints besides the normalization condition
$$p_1 + p_2 + \cdots + p_n = 1.$$
- We can set $p_1 = \cdots = p_n = \frac{1}{n}$.
- Given a complete lack of knowledge, all worlds are equally probable. That is, the distribution is uniform.

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Quiz: MaxEnt with One Constraint



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Quiz

For $\mathbf{P}(A, B) = (p_1, p_2, p_3, p_4)$, suppose the only constraint besides normalization is $P(B \mid A) = 1$. Which distribution is selected by MaxEnt?

- (a) $\mathbf{P}(A, B) = (1/4, 1/4, 1/4, 1/4)$.
- (b) $\mathbf{P}(A, B) = (1/3, 0, 1/3, 1/3)$.
- (c) $\mathbf{P}(A, B) = (1/2, 0, 0, 1/2)$.

Reasoning with Bayesian Networks

Graphical Representation of Knowledge as a Bayesian Network

A *Bayesian network* is a DAG with one CPT for each node; its graph encodes conditional-independence assumptions. In Ertel's presentation, a fully specified Bayesian network is a *structured special case of MaxEnt*: it adds independence assumptions and complete CPTs [Ertel 2025], p. 172.

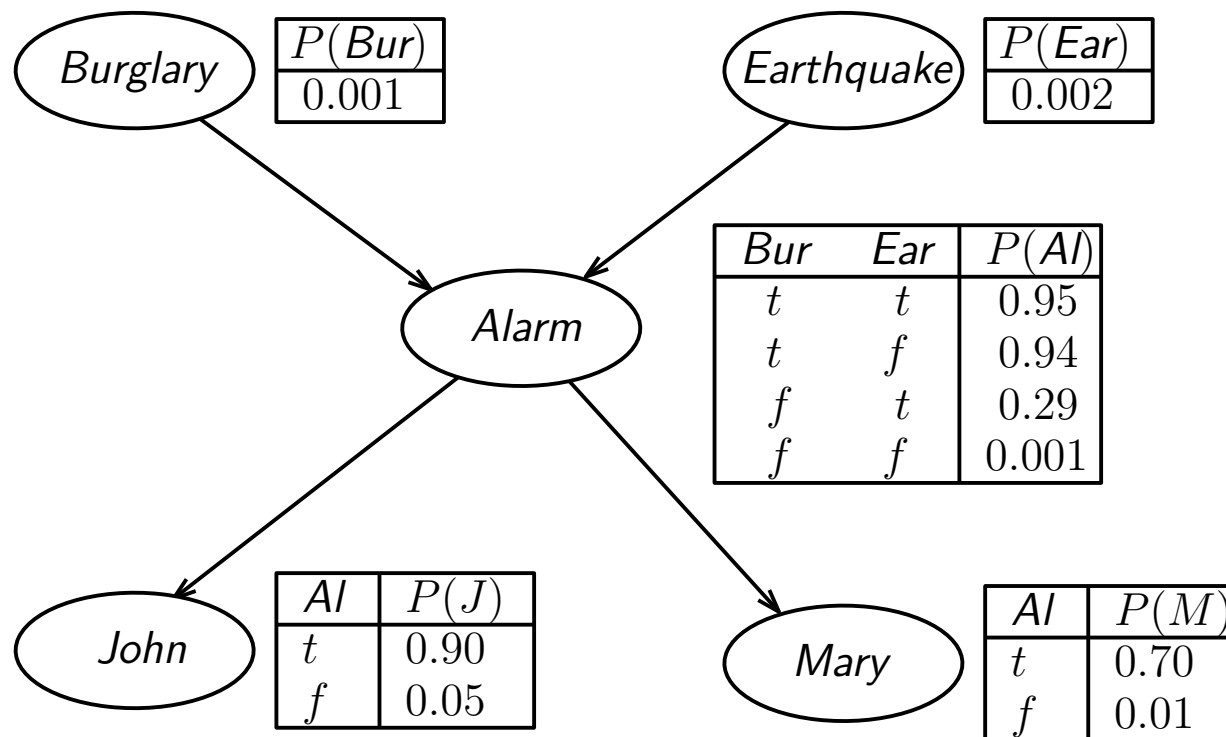


Figure: Alarm network and its CPTs.

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Definition

Two variables A and B are called *conditionally independent* given C if, for every a, b, c with $P(C = c) > 0$,

$$P(A = a, B = b \mid C = c) = P(A = a \mid C = c)P(B = b \mid C = c).$$

Remark

- independent $\nRightarrow$ conditionally independent.
- conditionally independent $\nRightarrow$ independent.
- *A and B are independent events* means knowing that A happened would not tell you anything about whether B happened (or vice versa).
- *A and B are conditionally independent events, given C* means that if you already knew that C happened, then knowing that A happened would not tell you further information about whether B happened.

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Example 3 (Alarm-Example (cont.))

- John and Mary independently react to an alarm.

$$\mathbf{P}(J, M \mid A) = \mathbf{P}(J \mid A) \cdot \mathbf{P}(M \mid A).$$

- Thus, *given an alarm, two variables J and M are independent.*

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Quiz: Conditioning on the Alarm



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Quiz

In the alarm example, Bur and Ear are independent. Suppose it is known that the alarm was triggered. Which relation is correct?

- (a) $P(Bur \mid Al, Ear) = P(Bur \mid Al, \neg Ear)$.
- (b) $P(Bur \mid Al, Ear) > P(Bur \mid Al, \neg Ear)$.
- (c) $P(Bur \mid Al, Ear) < P(Bur \mid Al, \neg Ear)$.

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Since *Bur* and *Ear* are independent, conditional marginalization gives

$$\begin{aligned}P(AI \mid Bur) &= P(AI \mid Bur, Ear)P(Ear) + P(AI \mid Bur, \neg Ear)P(\neg Ear) \\&= 0.95(0.002) + 0.94(0.998) = 0.94002,\end{aligned}$$

$$P(\neg AI \mid Bur) = 1 - P(AI \mid Bur) = 1 - 0.94002 = 0.05998.$$

Hence,

$$\begin{aligned}P(J \mid Bur) &= P(J \mid AI)P(AI \mid Bur) + P(J \mid \neg AI)P(\neg AI \mid Bur) \\&= 0.9 \cdot 0.94002 + 0.05 \cdot 0.05998 = 0.849017,\end{aligned}$$

$$\begin{aligned}P(M \mid Bur) &= P(M \mid AI)P(AI \mid Bur) + P(M \mid \neg AI)P(\neg AI \mid Bur) \\&= 0.7 \cdot 0.94002 + 0.01 \cdot 0.05998 = 0.6586138.\end{aligned}$$

Using the same marginalization,

$$\begin{aligned}P(J, M \mid Bur) &= P(J \mid AI)P(M \mid AI)P(AI \mid Bur) \\&\quad + P(J \mid \neg AI)P(M \mid \neg AI)P(\neg AI \mid Bur) \\&= 0.9 \cdot 0.7 \cdot 0.94002 + 0.05 \cdot 0.01 \cdot 0.05998 \\&= 0.59224259 \approx 0.5922.\end{aligned}$$

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Quiz: Independence Given a Burglary



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Quiz

Use the practical calculations above to test whether J and M are independent given Bur . Which relation is correct?

- (a) $P(J, M \mid Bur) = P(J \mid Bur)P(M \mid Bur).$
- (b) $P(J, M \mid Bur) > P(J \mid Bur)P(M \mid Bur).$
- (c) $P(J, M \mid Bur) < P(J \mid Bur)P(M \mid Bur).$

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Construction of a Bayesian network

- **Step 1:** *Choose variables and an ordering.* Choose the variables and an ordering $X_1, \dots, X_n$. Any ordering is allowed; *causes before effects often yields a simpler network.*
- **Step 2:** *Select a minimal parent set.* For each X_i , choose an inclusion-minimal set $\text{Parents}(X_i) \subseteq \{X_1, \dots, X_{i-1}\}$. It must satisfy $\mathbf{P}(X_i \mid X_1, \dots, X_{i-1}) = \mathbf{P}(X_i \mid \text{Parents}(X_i))$ for every assignment for which the conditional probabilities are defined. *Inclusion-minimal* means that *no selected parent can be removed while preserving this equality.*
- **Step 3:** *Add the edges.* For every selected parent $X_j \in \text{Parents}(X_i)$, *add the directed edge* $X_j \rightarrow X_i$.
- **Step 4:** *Specify the CPTs.* For every node, specify $\mathbf{P}(X_i \mid \text{Parents}(X_i))$: *list the probability of each value of X_i for every combination of its parents' values.*

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- The alarm example used one *causes-before-effects ordering*; the construction algorithm *permits any variable ordering*.
- A causes-before-effects ordering often gives *fewer parents* and makes the required probability assessments *easier to understand*.
- A *poor ordering* may require *more edges and CPT parameters*, even though the resulting network can represent the same joint distribution.

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Quiz: Parent Selection with a Different Ordering



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Quiz

For the alarm example, use the altered variable ordering (M, Al, Ear, Bur, J) . When Bur is added, which parent set satisfies the parent-selection condition and is **inclusion-minimal** (no selected parent can be removed)?

- (a) $\text{Parents}(Bur) = \{Al\}$.
- (b) $\text{Parents}(Bur) = \{Al, Ear\}$.
- (c) $\text{Parents}(Bur) = \{M, Al, Ear\}$.

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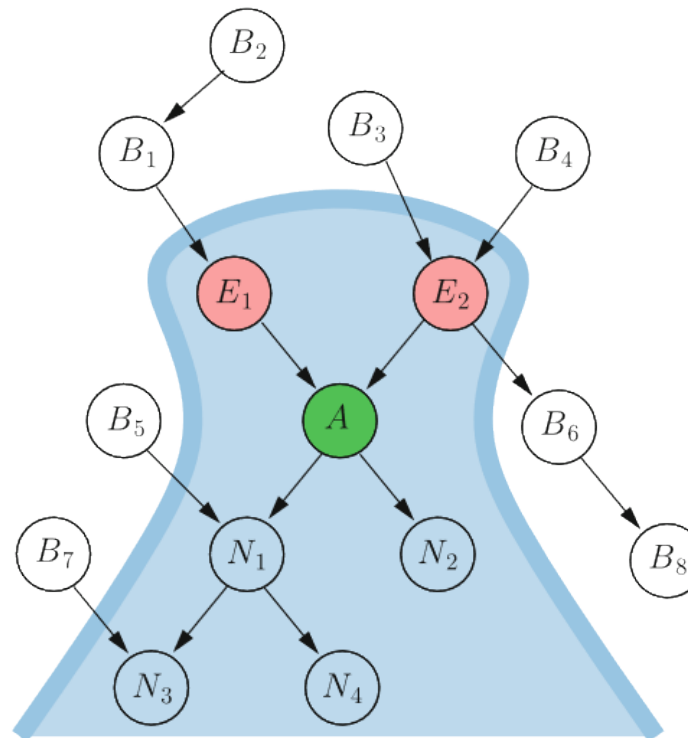
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Theorem 3

Given its *parents*, a node in a Bayesian network is *conditionally independent* of the set of all other nodes that are neither its *descendants* nor its *parents* [Ertel 2025], p. 170.

Example of conditional independence in a Bayesian network. Given its parents E_1 and E_2 , A is *conditionally independent* of the set of non-descendant nodes $B_1, \dots, B_8$.



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Quiz: Applying the Network Semantics



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Quiz

For the completed alarm network, which equality follows from Theorem 3?

- (a) $\mathbf{P}(Al \mid Bur, Ear, J, M) = \mathbf{P}(Al \mid Bur, Ear).$
- (b) $\mathbf{P}(J \mid Al, Bur, Ear, M) = \mathbf{P}(J \mid Al).$
- (c) $\mathbf{P}(Bur \mid Al, Ear) = \mathbf{P}(Bur \mid Al).$

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- The pointwise chain rule and the parent-selection condition yield the *Bayesian-network factorization*; the CPTs supply a row for every parent assignment:

$$\mathbf{P}(X_1, \dots, X_n) = \prod_{i=1}^n \mathbf{P}(X_i \mid \text{Parents}(X_i)).$$

- Applying this factorization to the completed alarm network gives

$$\begin{aligned} &\mathbf{P}(Bur, Ear, Al, J, M) \\ &= \mathbf{P}(Bur)\mathbf{P}(Ear)\mathbf{P}(Al \mid Bur, Ear)\mathbf{P}(J \mid Al)\mathbf{P}(M \mid Al). \end{aligned}$$

Reasoning with Bayesian Networks

Quiz: Factorization and Marginalization



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Quiz

In the completed alarm network, which expression computes $P(J, M, Bur)$? Here $a \in \{Al, \neg Al\}$ and $e \in \{Ear, \neg Ear\}$.

- (a) $P(Bur)P(J | Bur)P(M | Bur)$.
- (b) $P(Bur)P(Ear)P(Al | Bur, Ear)P(J | Al)P(M | Al)$.
- (c) $\sum_{a,e} P(Bur)P(e)P(a | Bur, e)P(J | a)P(M | a)$.

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Conditional Marginalization

- If $P(B) > 0$, write c for the event $C = c$ and let $S_B := \{c : P(B, c) > 0\}$. Then

$$P(A \mid B) = \sum_{c \in S_B} P(A \mid B, c)P(c \mid B).$$

- If C and B are independent, then $P(c \mid B) = P(c)$.

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Reasoning with Bayesian Networks

Quiz: Removing the Earthquake Node



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Quiz

In the alarm network, remove *Ear* while keeping all probabilities involving only *Bur*, *Al*, *J*, *M* unchanged. Recall that *Bur* and *Ear* are independent. For $b \in \{Bur, \neg Bur\}$ and $e \in \{Ear, \neg Ear\}$, which update is correct?

- (a) Only the alarm CPT changes, using $P(Al \mid b) = P(Al \mid b, \neg Ear)$.
- (b) Only the alarm CPT changes, using $P(Al \mid b) = \sum_e P(Al \mid b, e)P(e)$.
- (c) The alarm, John, and Mary CPTs must all be recomputed by marginalizing over *Ear*.

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