

AFSA B01 Group: SSSS 2022.05

# On Reconfiguration Graph of Independent Sets under Token Sliding

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(A research starting from SSSW 2021.04 @ Kyoto)

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## Realizing $TS_k$ -Reconfiguration Graphs

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- $L(G)$  and  $TS_2(\overline{G})$
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- Paths and Cycles
- Complete Bipartite Graphs

## Graph Properties: $G$ vs. $TS_k(G)$ and $TS(G)$

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- Can Forests Be  $TS_k$ -Graphs?

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# TS-Reconfiguration Graphs

## Introduction



Given a graph  $G = (V, E)$  and a positive integer  $k$ .

	$G$
Vertex	$V(G)$
Edge	$E(G)$

- Each vertex of  $G$  contains at most *one unlabeled* token.

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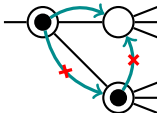
## Introduction



Given a graph  $G = (V, E)$  and a positive integer  $k$ .

	$G$
Vertex	$V(G)$
Edge	$E(G)$

- Each vertex of  $G$  contains at most *one unlabeled* token.
- *Token Sliding* involves moving a token from one vertex to one of its *unoccupied adjacent* vertices.



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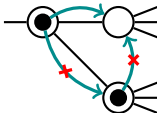
Given a graph  $G = (V, E)$  and a positive integer  $k$ .

	$G$	<i>Token Graph <math>F_k(G)</math></i>
Vertex	$V(G)$	$k$ -Vertex Subsets of $V(G)$
Edge	$E(G)$	Token Sliding

Well-known variants of  $F_k(G)$  involve 15-PUZZLE, PEBBLE MOTION, CHIP-FIRING GAME, ROBOT MOTION, and so on

$F_2(G)$  [Alavi, Behzad, Erdős, and Lick 1991]

- Each vertex of  $G$  contains at most *one unlabeled* token.
- Token Sliding* involves moving a token from one vertex to one of its *unoccupied adjacent* vertices.



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Given a graph  $G = (V, E)$  and a positive integer  $k$ .

	$G$	<i>Token Graph</i> $F_k(G)$	<i><math>TS_k</math>-(Reconfiguration) Graph</i> $TS_k(G)$
Vertex	$V(G)$	$k$ -Vertex Subsets of $V(G)$	<i>Independent</i> $k$ -Vertex Subsets of $V(G)$
Edge	$E(G)$	Token Sliding	Token Sliding

$F_2(G)$  [Alavi, Behzad, Erdős, and Lick 1991]

[This Talk]

- Each vertex of  $G$  contains at most *one unlabeled* token.
- Token Sliding* involves moving a token from one vertex to one of its *unoccupied adjacent* vertices.

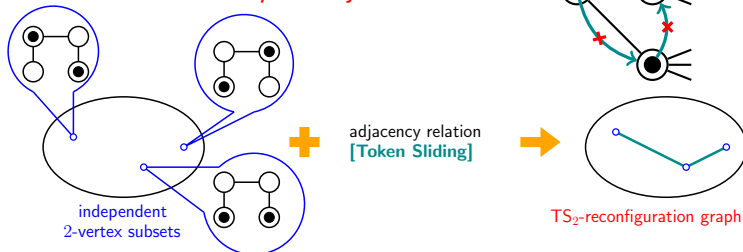


Figure:  $TS_2(P_4) \subseteq F_2(P_4)$

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## Introduction



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In this talk, we focus on two graphs:

- $TS_k(G)$  whose nodes are independent sets of *size- $k$* , and
- $TS(G)$  whose nodes are independent sets of *arbitrary size*.

### Note

- $TS_k(G)$  is an induced subgraph of  $TS(G)$ .
- $TS_k(G)$  may *not* be a component of  $TS(G)$ .
- $k = 1$  is not interesting, since  $G \simeq TS_1(G)$  for any graph  $G$ . Therefore *we always consider  $k \geq 2$* .

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A More General Framework



## Reconfiguration Setting

- Moving from one *state/configuration* to another
  - The whole state space is *not* given, but you can, in polynomial-time, check if a state is “valid”.
- ... using a pre-defined (*reconfiguration*) *rule*
  - You can, in polynomial-time, check if one “valid” state can be transformed to another by using the rule *exactly once*.

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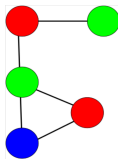
## Reconfiguration Setting

- Moving from one *state/configuration* to another
- ... using a pre-defined (*reconfiguration*) *rule*

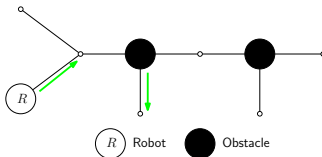
### ■ Games & Puzzles.



### ■ Frequency Re-Assignment.



### ■ Robot Motion.



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### References

- “Reconfiguration of Independent Sets” is one of the most well-studied topics in the Reconfiguration framework.
- Most of the previous research on  $TS_k(G)$  have been focused on *designing efficient algorithms* and *showing computational hardness* of several reconfiguration questions [Nishimura 2018].
  - REACHABILITY/SHORTEST TRANSFORMATION: Is there a (shortest) path between two given nodes of  $TS_k(G)$ ?
  - CONNECTIVITY: Is  $TS_k(G)$  connected?
  - and so on.

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  - REACHABILITY/SHORTEST TRANSFORMATION: Is there a (shortest) path between two given nodes of  $TS_k(G)$ ?
  - CONNECTIVITY: Is  $TS_k(G)$  connected?
  - and so on.

## Our Goal

We look at  $TS_k(G)$  from *a purely graph-theoretic viewpoint*.

- What are the necessary and sufficient conditions for  $TS_k(G)$  to be in some graph class  $\mathcal{G}$ ?
- If  $G$  satisfies some property  $\mathcal{P}$ , does  $TS(G)/TS_k(G)$  also satisfy  $\mathcal{P}$ , and vice versa?

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- If  $H$  and  $G$  are isomorphic, then so are  $TS_k(H)$  and  $TS_k(G)$ . *The reverse does not hold.*
- If  $H$  is an induced subgraph of  $G$ , then  $TS_k(H)$  is an induced subgraph of  $TS_k(G)$ . *The reverse does not hold.*

$i$	$G_i$	$TS_2(G_i)$
1		
2		
3		

# Realizing $TS_k$ -Reconfiguration Graphs

## Our Results



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### Main Question

*Is  $G$  a  $TS_k$ -graph?*

More precisely, does there exist a graph  $H$  such that  $G \simeq_f TS_k(H)$ , where  $f : V(G) \rightarrow V(TS_k(H))$  is bijective and  $uv \in E(G)$  if and only if  $f(u)f(v) \in E(TS_k(H))$ ?

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### Our Results

- There is a relationship between the *line graph of  $G$*  and the  *$TS_2$ -graph of its complement  $\overline{G}$* .
- All *complete graphs*, *paths*, and *cycles* are  $TS_k$ -graphs.
- Characterize which *complete bipartite graphs* and *connected split graphs* are  $TS_k$ -graphs.

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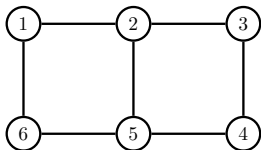
# Realizing $TS_k$ -Reconfiguration Graphs

Line graph  $L(G)$  and  $TS_2$ -graph  $TS_2(\overline{G})$

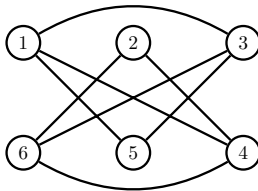


## Lemma 1

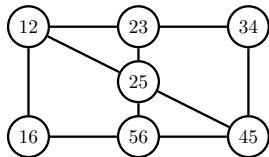
- $TS_2(\overline{G})$  is a (spanning) subgraph of  $L(G)$ .
- $TS_2(\overline{G}) \simeq L(G)$  if and only if  $G$  is triangle-free.



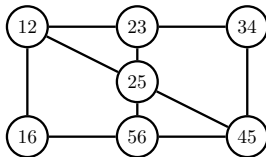
$G$



$\overline{G}$



$L(G)$



$TS_2(\overline{G})$

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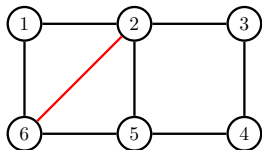
# Realizing $TS_k$ -Reconfiguration Graphs

Line graph  $L(G)$  and  $TS_2$ -graph  $TS_2(\overline{G})$

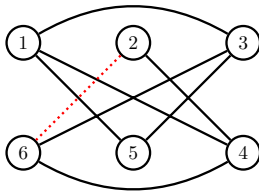


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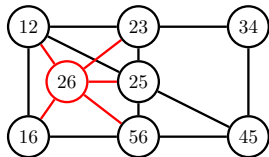
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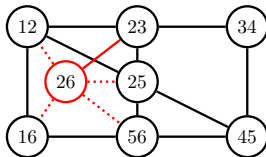
$G$



$\overline{G}$



$L(G)$



$TS_2(\overline{G})$

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# Realizing $TS_k$ -Reconfiguration Graphs

## Complete Graphs



### Lemma 2

Given  $H$  and let  $G = TS_{\alpha(H)}(H)$ . Then, for every  $k \geq \alpha(H)$ ,  $G$  is a  $TS_k$ -graph.

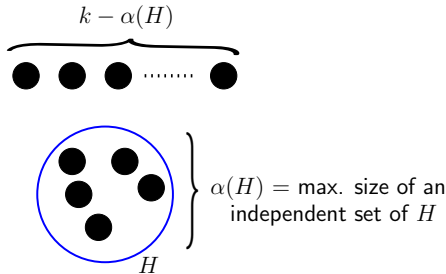


Figure: A graph  $H'$  s.t.  $G = TS_{\alpha(H)}(H) \simeq TS_k(H')$  for  $k \geq \alpha(H)$ .

### Corollary 3

$K_n$  is a  $TS_k$ -graph for every  $k \geq 1$ .

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## Paths and Cycles



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### Proposition 4

$P_n$  is a  $TS_k$ -graph.

- (suggested by Yuni IWAMASA.) For  $k = 2$ , use Lemma 1.

$$P_n = L(P_{n+1}) \simeq TS_2(\overline{P_{n+1}}).$$

- For  $k \geq 3$ , note that  $\alpha(\overline{P_{n+1}}) = 2$ . Use Lemma 2.

### Proposition 5

$C_n$  is a  $TS_k$ -graph ( $n \geq 4$ ).

- For  $k = 2$ , use Lemma 1.

$$C_n = L(C_n) \simeq TS_2(\overline{C_n}).$$

- For  $k \geq 3$ , note that  $\alpha(\overline{C_n}) = 2$ . Use Lemma 2.

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# Realizing $TS_k$ -Reconfiguration Graphs

A Different Approach for Paths



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## Key Idea ( $k = 2$ )

There exists  $G$  such that  $P_1 \simeq TS_2(G)$ . For  $n \geq 2$ , we *update*  $G$  and label vertices of  $P_n$  by size-2 independent sets of  $G$ .

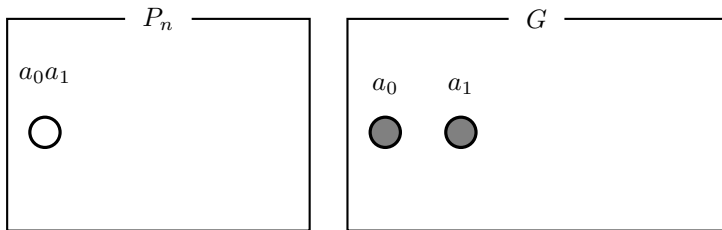


Figure:  $P_n$  is a  $TS_2$ -graph.

**Note:**  $G \simeq \overline{P_{n+1}}$ .

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A Different Approach for Paths



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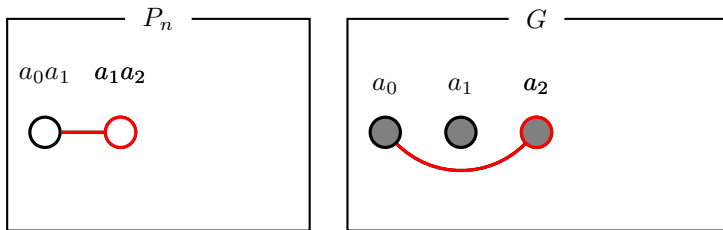


Figure:  $P_n$  is a  $TS_2$ -graph.

**Note:**  $G \simeq \overline{P_{n+1}}$ .

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There exists  $G$  such that  $P_1 \simeq TS_2(G)$ . For  $n \geq 2$ , we *update*  $G$  and label vertices of  $P_n$  by size-2 independent sets of  $G$ .

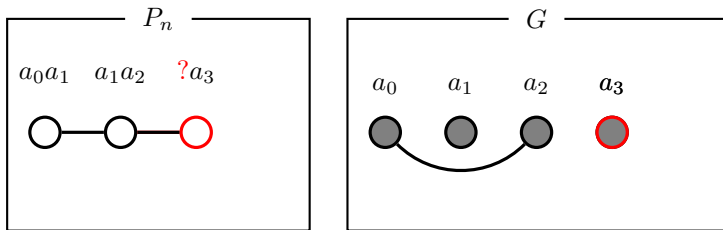


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# Realizing $TS_k$ -Reconfiguration Graphs

A Different Approach for Paths



Avis and Hoang

## Key Idea ( $k = 2$ )

There exists  $G$  such that  $P_1 \simeq TS_2(G)$ . For  $n \geq 2$ , we *update*  $G$  and label vertices of  $P_n$  by size-2 independent sets of  $G$ .

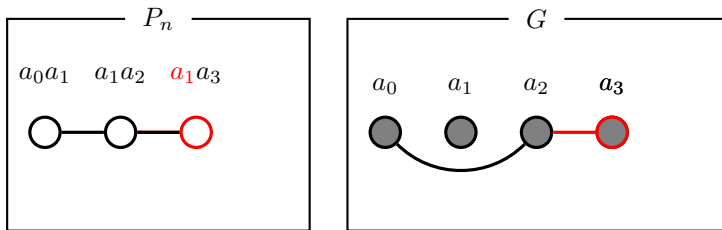


Figure:  $P_n$  is a  $TS_2$ -graph.

**Note:**  $G \simeq \overline{P_{n+1}}$ .

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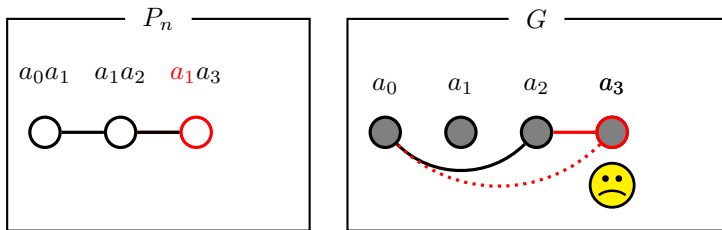


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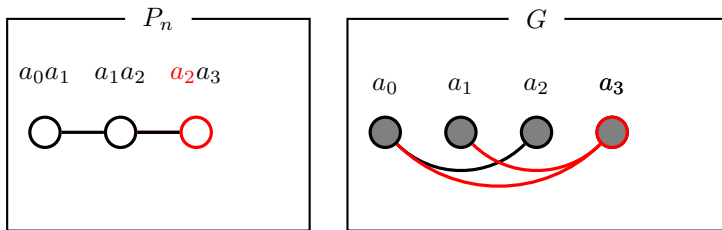


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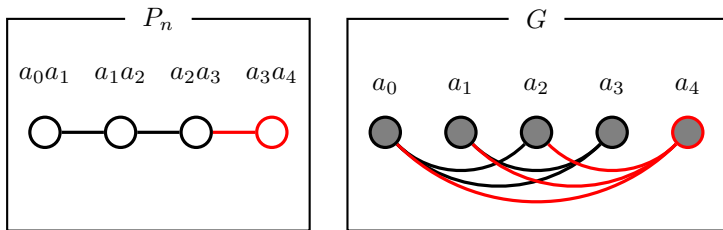


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### Proposition 6

$K_{m,n}$  ( $m \leq n$ ) is a  $TS_k$ -graph  $\Leftrightarrow$  either  $m = 1$  and  $n \leq k$  or  $m = n = 2$ .

( $\Leftarrow$ ) Since  $K_{2,2} \simeq C_4$ , the case  $m = n = 2$  is trivial. If  $m = 1$  and  $n \leq k$ , we construct  $G$  such that  $K_{m,n} \simeq TS_k(G)$ .

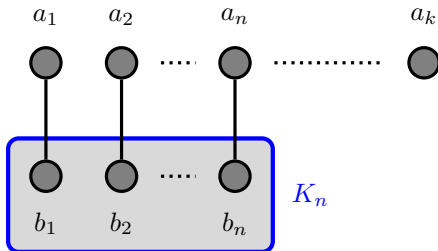


Figure: A graph  $G$  such that  $K_{1,n} \simeq TS_k(G)$  where  $n \leq k$ .

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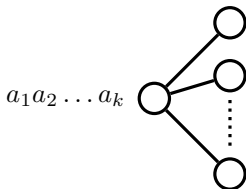


Figure:  $K_{m,n}$  is not a  $TS_k$ -graph when  $m = 1$  and  $n \geq k + 1$ .

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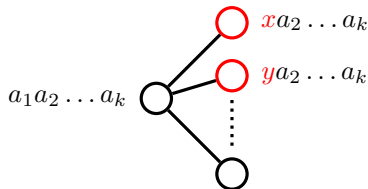
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Pigeonhole principle

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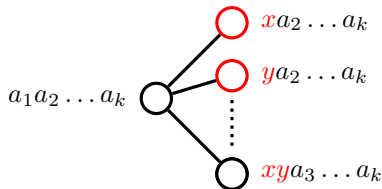
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Pigeonhole principle

How about  
 $xya_3 \dots a_k$ ? ☹️

Figure:  $K_{m,n}$  is not a  $TS_k$ -graph when  $m = 1$  and  $n \geq k + 1$ .

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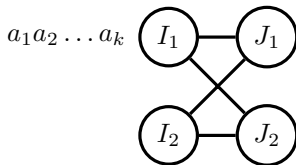
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How can we label the rest?

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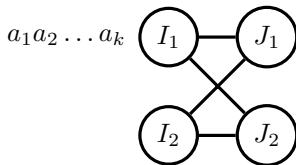
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How can we label the rest?

At most two tokens can move from their original positions

Figure:  $K_{m,n}$  is not a  $TS_k$ -graph when  $m \geq 2$  and  $n > 2$ .

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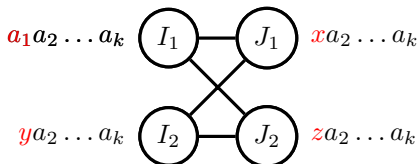
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How can we label the rest?

If *one token* can move from its original position

Figure:  $K_{m,n}$  is not a  $TS_k$ -graph when  $m \geq 2$  and  $n > 2$ .

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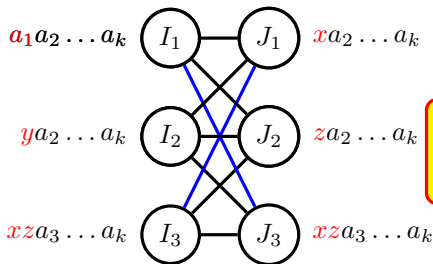
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How about

$x z a_3 \dots a_k$ ? 😞

If **one token** can move from its original position

Figure:  $K_{m,n}$  is not a  $TS_k$ -graph when  $m \geq 2$  and  $n > 2$ .

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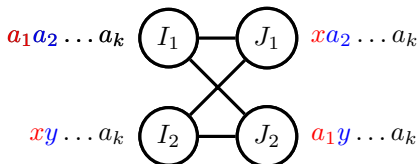
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How can we label the rest?

If *two tokens* can move from their original position

Figure:  $K_{m,n}$  is not a  $TS_k$ -graph when  $m \geq 2$  and  $n > 2$ .

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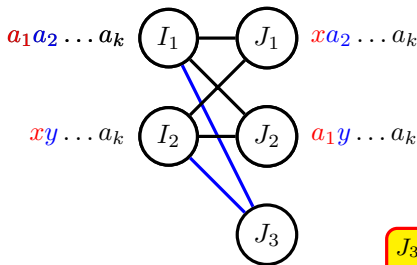
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How can we label  $J_3$ ? 😊

If *two tokens* can move from their original position

$J_3$  contains one member of  $\{a_1, a_2\}$  and one of  $\{x, y\}$ .

Figure:  $K_{m,n}$  is not a  $TS_k$ -graph when  $m \geq 2$  and  $n > 2$ .

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# Graph Properties: $G$ vs. $TS_k(G)$ and $TS(G)$

## Our Results



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### Main Question

*If  $G$  satisfies a graph property  $\mathcal{P}$ , does  $TS(G)/TS_k(G)$  satisfy  $\mathcal{P}$  too, and vice versa?*

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## Main Question

*If  $G$  satisfies a graph property  $\mathcal{P}$ , does  $TS(G)/TS_k(G)$  satisfy  $\mathcal{P}$  too, and vice versa?*

## Our Results

We answered the question for the following properties  $\mathcal{P}$ :

- $s$ -Partite
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- Eulerian
- (Non-)acyclic
- The clique's size

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$\mathcal{P}$	$G$	(a)	(b)	(c)	(d)
$s$ -partite	general	yes			no
planar	$P_n$	yes, iff $n \leq 8$		yes, iff $k = 2, n \geq 3$ or $k \geq 3, n \leq 8$	
	tree	yes, iff $n \leq 7$			
	$C_n$	yes, iff $n \leq 6$			
	connected				
Eulerian	$C_n$	no	yes	yes	
	general	no	yes	no	no
acyclic	$P_n$	yes, iff $n \leq 4$			
non-acyclic	$C_n$	no	yes, iff $1 \leq k < n/2$		
having $K_s$	general	yes		no	yes

**Table:** Some properties of (reconfiguration) graphs. Here  $n = |V(G)|$ . There are four cases: (a)  $\mathcal{P}(G) \Rightarrow \mathcal{P}(TS(G))$ , (b)  $\mathcal{P}(TS(G)) \Rightarrow \mathcal{P}(G)$ , (c)  $\mathcal{P}(G) \Rightarrow \mathcal{P}(TS_k(G))$ , and (d)  $\mathcal{P}(TS_k(G)) \Rightarrow \mathcal{P}(G)$ . ( $\mathcal{P}(G) \Rightarrow \mathcal{P}(H)$  means if  $G$  satisfies property  $\mathcal{P}$  then  $H$  satisfies  $\mathcal{P}$ .)

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A **proper  $s$ -coloring**  $f : V(G) \rightarrow \{0, \dots, s-1\}$  of  $G$  is a mapping such that  $f(u) \neq f(v)$  if  $uv \in E(G)$ . The **chromatic number**  $\chi(G)$  of a graph  $G$  is the smallest  $s$  such that  $G$  has a proper  $s$ -coloring.

### $s$ -Partite

- $G$  is  $s$ -partite  $\Leftrightarrow TS(G)$  is  $s$ -partite. In other words,  $\chi(G) = \chi(TS(G)) \geq \chi(TS_k(G))$ .
- (by Masahiro TAKAHASHI.) Let  $f : V(G) \rightarrow \{0, \dots, s-1\}$  be a proper  $s$ -coloring of  $G$ . Then  $g : V(TS(G)) \rightarrow \{0, \dots, s-1\}$  defined by  $g(I) = \sum_{v \in I} f(v) \pmod s$  is a proper  $s$ -coloring of  $TS(G)$ .

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# Graph Properties: $G$ vs. $TS_k(G)$ and $TS(G)$

$s$ -Partite



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A **proper  $s$ -coloring**  $f : V(G) \rightarrow \{0, \dots, s-1\}$  of  $G$  is a mapping such that  $f(u) \neq f(v)$  if  $uv \in E(G)$ . The **chromatic number**  $\chi(G)$  of a graph  $G$  is the smallest  $s$  such that  $G$  has a proper  $s$ -coloring.

## $s$ -Partite

- $G$  is  $s$ -partite  $\Leftrightarrow TS(G)$  is  $s$ -partite. In other words,  $\chi(G) = \chi(TS(G)) \geq \chi(TS_k(G))$ .
  - (by Masahiro TAKAHASHI.) Let  $f : V(G) \rightarrow \{0, \dots, s-1\}$  be a proper  $s$ -coloring of  $G$ . Then  $g : V(TS(G)) \rightarrow \{0, \dots, s-1\}$  defined by  $g(I) = \sum_{v \in I} f(v) \pmod s$  is a proper  $s$ -coloring of  $TS(G)$ .
- There exists a graph  $G$  such that  $\chi(TS_k(G)) < \chi(G)$ .
  - Take a graph  $G$  having a vertex  $v$  that is adjacent to all other vertices and let  $G' = G - v$ . We have  $\chi(G) = \chi(G') + 1 \geq \chi(TS_k(G')) + 1 = \chi(TS_k(G)) + 1$ .

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# Graph Properties: $G$ vs. $TS_k(G)$ and $TS(G)$

## Eulerian



A graph  $G$  is *Eulerian*  $\Leftrightarrow G$  is connected and all vertices of  $G$  have even degree.

### Eulerian

- $TS_k(C_n)$  is *Eulerian*, for  $1 \leq k < n/2$ .
  - For  $1 \leq k < n/2$ ,  $TS_k(C_n)$  is connected. Take any  $I \in TS_k(C_n)$ . Only maximal paths  $P = v_1 v_2 \dots v_{2i+1}$  in  $C_n$  satisfying  $\{v_1, v_3, \dots, v_{2i+1}\} \subseteq I$  affect the degree of  $I$ . (Each path contributes 0 or 2.)

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- For any *Eulerian graph*  $G$  on  $n \geq 4$  vertices, *every component of  $TS_2(G)$  is Eulerian*.
  - Every vertex of  $TS_2(G)$  has even degree.

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# Graph Properties: $G$ vs. $TS_k(G)$ and $TS(G)$

Eulerian



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- $TS_k(C_n)$  is *Eulerian*, for  $1 \leq k < n/2$ .
  - For  $1 \leq k < n/2$ ,  $TS_k(C_n)$  is connected. Take any  $I \in TS_k(C_n)$ . Only maximal paths  $P = v_1 v_2 \dots v_{2i+1}$  in  $C_n$  satisfying  $\{v_1, v_3, \dots, v_{2i+1}\} \subseteq I$  affect the degree of  $I$ . (Each path contributes 0 or 2.)
- For any *Eulerian graph*  $G$  on  $n \geq 4$  vertices, *every component of  $TS_2(G)$  is Eulerian*.
  - Every vertex of  $TS_2(G)$  has even degree.
- There exists an *Eulerian graph*  $G$  where  $TS_k(G)$  is *not Eulerian*, for any  $k \in \{3, \dots, \alpha(G)\}$ .
- For any graph  $G$ , if  $TS(G)$  is Eulerian, so is  $G$ . Moreover, for any  $k \geq 2$ , one can construct a graph  $G$  such that  $G$  is *not Eulerian but  $TS_k(G)$  is*.

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# Graph Properties: $G$ vs. $TS_k(G)$ and $TS(G)$

Eulerian



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$k$	(a)		(b)	
	$G$	$TS_k(G)$	$G$	$TS_k(G)$
$k = 2$		disconnected		$C_3$
$k \geq 3$		has degree-3 vertex		$C_4$

**Figure:** (a)  $G$  is Eulerian and  $TS_k(G)$  is not, (b)  $G$  is not Eulerian and  $TS_k(G)$  is.

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# Graph Properties: $G$ vs. $TS_k(G)$ and $TS(G)$

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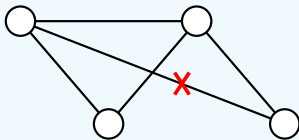


## The Clique's Size

■  $G$  has a  $K_n \Leftrightarrow TS(G)$  has a  $K_n$  ( $n \geq 3$ ).

■ If  $TS_k(G)$  has a  $K_3$ , so does  $G$ .

$$I_1 = \{a_1, a_2, \dots, a_k\} \quad I_2 = \{x, a_2, \dots, a_k\}$$



$$I_3 = \{y, a_2, \dots, a_k\} \quad I_3 = \{x, z, \dots, a_k\}$$

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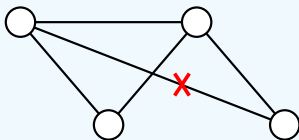
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## The Clique's Size

■  $G$  has a  $K_n \Leftrightarrow TS(G)$  has a  $K_n$  ( $n \geq 3$ ).

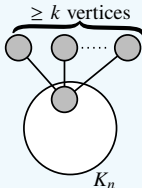
■ If  $TS_k(G)$  has a  $K_3$ , so does  $G$ .

$$I_1 = \{a_1, a_2, \dots, a_k\} \quad I_2 = \{x, a_2, \dots, a_k\}$$



$$I_3 = \{y, a_2, \dots, a_k\} \quad I_3 = \{x, z, \dots, a_k\}$$

■ There exists a graph  $G$  s.t.  $G$  has a  $K_n$  and  $TS_k(G)$  ( $k \geq 2$ ) does not.



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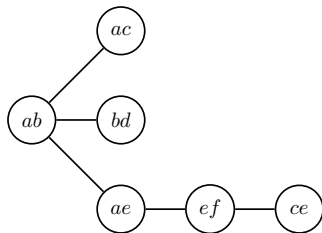
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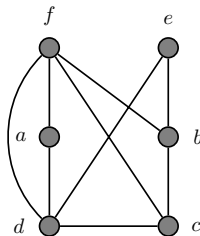
## Open Question

A forest  $T$  is a  $TS_k$ -graph  $\Leftrightarrow$  ?

**Remark:** “Being a  $TS_k$ -graph” is not hereditary even for trees. For example,  $K_{1,3}$  is not a  $TS_2$ -graph, but the graph obtained by replacing an edge of  $K_{1,3}$  by a  $P_4$  is.



$$T \simeq TS_2(G)$$



$G$

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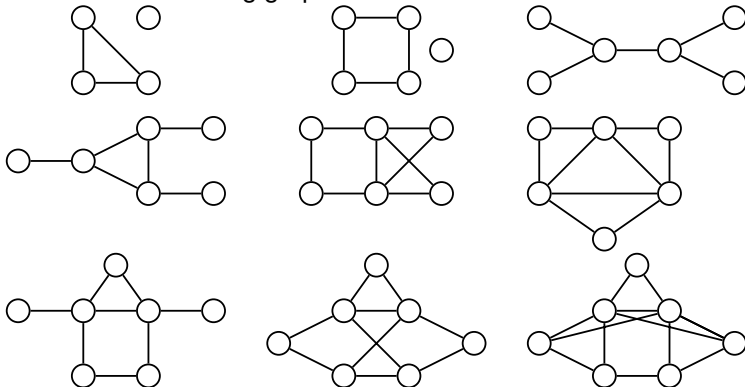


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We have constructed a (complete?) list  $\mathcal{G}$  of graphs such that *if  $TS_2(G)$  is a forest,  $G$  must not contain any member of  $\mathcal{G}$  as an induced subgraph.* (Thanks to Jesper JANSSEN for helpful discussions.)

■  $\overline{C_n}$  ( $n \geq 4$ ),

■ and the following graphs:



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## Can Forests Be $TS_k$ -Graphs?



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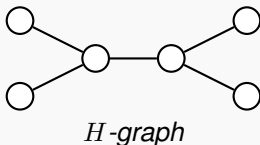
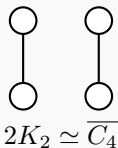
### Note

If  $TS_2(G)$  is a forest,  $G$  is a *weakly chordal graph* ( $\subseteq$  perfect graph).

- $G$  is  $\overline{C_4}$ -free  $\Leftrightarrow G$  is  $2K_2$ -free  $\Rightarrow G$  is  $C_n$ -free ( $n \geq 6$ ).
- $G$  is  $\overline{C_n}$ -free ( $n \geq 4$ )  $\Rightarrow G$  is  $(C_n, \overline{C_n})$ -free ( $n \geq 5$ )  $\Leftrightarrow G$  is weakly chordal ( $\subseteq$  perfect).

## Proposition 7

Let  $F$  be a forest.  $TS_2(F)$  is a forest  $\Leftrightarrow F$  is  $(2K_2, H)$ -free.



Consequently,

Let  $F$  be a tree.  $TS_2(F)$  is a tree  $\Leftrightarrow F \simeq P_n$  ( $1 \leq n \leq 4$ ).

$(\Rightarrow)$   $TS_2(2K_2) \simeq C_4$  and  $TS_2(H) \simeq C_8 + 2K_1$ .

$(\Leftarrow)$  If  $F$  has a cycle and is  $2K_2$ -free, it contains an induced  $H$ -graph.

## Question

Let  $G$  be a non-acyclic graph. Then  $TS_2(G)$  is a forest  $\Leftrightarrow ?$

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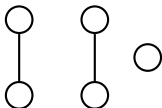
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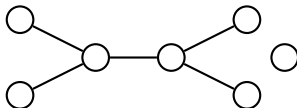
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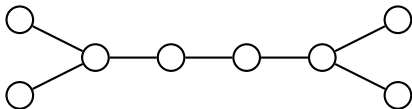
- Let  $F$  be a forest. *If  $TS_3(F)$  is a forest,  $F$  does not contain any of the following graphs as an induced subgraph*



$2K_2 + K_1$



$H + K_1$



$H'$

### Question

If  $TS_3(F)$  has a cycle, does  $F$  contain one of the above graphs as an induced subgraph?

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Part I

Appendix

# Realizing $TS_k$ -Reconfiguration Graphs

## Connected Split Graphs



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1 Connected Split Graphs

Graph Properties:  $G$   
vs.  $TS_k(G)$  and  
 $TS(G)$

Planar

Girth

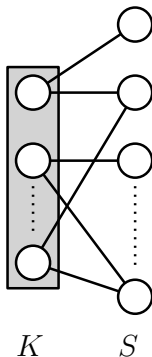


Figure: A split graph  $G = (K \cup S, E)$ .

### Recall

Every split graph  $G$  has a  $KS$ -partition such that  $|K| = \omega(G)$ —the maximum size of a clique of  $G$ . We denote it by  $G = (K \cup S, E)_{K\text{-max}}$ .

# Realizing $TS_k$ -Reconfiguration Graphs

## Connected Split Graphs



### Proposition 8

A connected  $G = (K \cup S, E)_{K\text{-max}}$  is a  $TS_k$ -graph  $\Leftrightarrow$  every  $v \in K$  has at most  $k - 1$  neighbors in  $S$  and every  $w \in S$  has exactly one neighbor in  $K$ .

( $\Leftarrow$ ) We construct a graph  $H$  such that  $G = TS_k(H)$ .

( $\Rightarrow$ ) How do we label  $G$  here?

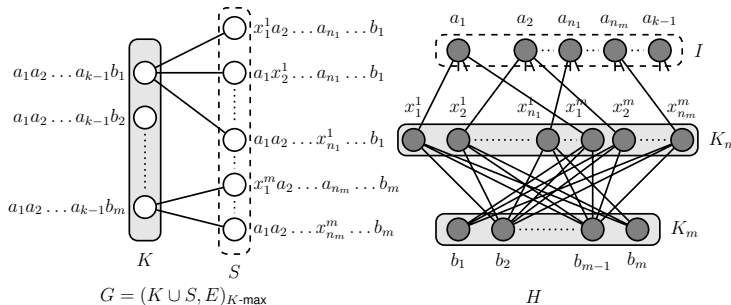


Figure: Construction of a graph  $H$  such that  $G \simeq TS_k(H)$ .

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Graph Properties:  $G$   
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Planar  
Girth

# Graph Properties: $G$ vs. $TS_k(G)$ and $TS(G)$

Planar



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Graph Properties:  $G$   
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Planar  
Girth

## Planar

- If  $G$  is non-planar, so is  $TS(G)$ . ( $G \simeq TS_1(G)$ )

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# Graph Properties: $G$ vs. $TS_k(G)$ and $TS(G)$

Planar



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Graph Properties:  $G$   
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 $TS(G)$

Planar  
Girth

## Planar

- If  $G$  is non-planar, so is  $TS(G)$ . ( $G \simeq TS_1(G)$ )
- [Computer search] With respect to the number of vertices,  $C_7$  is the unique smallest planar graph  $G$  for which  $TS(G)$  is non-planar.
  - For each of 99 connected planar graphs  $G$  on 6 vertices,  $TS(G)$  is planar.
  - $TS_2(C_7)$  is non-planar.

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# Graph Properties: $G$ vs. $TS_k(G)$ and $TS(G)$

Planar



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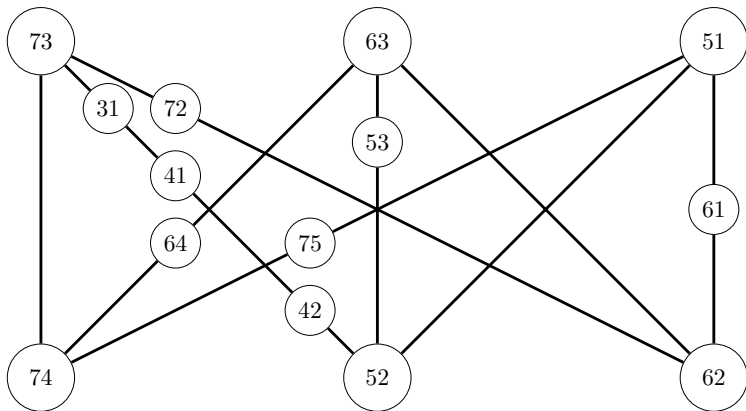
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3

Planar  
Girth



**Figure:** A subdivision of  $K_{3,3}$  that is contained in  $TS_2(C_7)$ . Each number of the form  $ab$  inside a node represents an independent set  $\{v_a, v_b\}$  of  $C_7 = v_1 \dots v_7 v_1$ .

# Graph Properties: $G$ vs. $TS_k(G)$ and $TS(G)$

Planar



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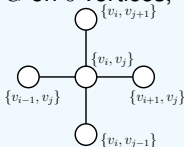
Graph Properties:  $G$   
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 $TS(G)$

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Planar  
Girth

## Planar

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- [Computer search] With respect to the number of vertices,  $C_7$  is the unique smallest planar graph  $G$  for which  $TS(G)$  is non-planar.
  - For each of 99 connected planar graphs  $G$  on 6 vertices,  $TS(G)$  is planar.
  - $TS_2(C_7)$  is non-planar.
- $TS_2(P_n)$  is planar for every  $n \geq 3$ .
  - $TS_2(P_n)$  is a subgraph of a  $n \times n$  grid.



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# Graph Properties: $G$ vs. $TS_k(G)$ and $TS(G)$

Planar



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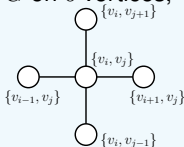
Graph Properties:  $G$   
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Planar  
Girth

## Planar

- If  $G$  is non-planar, so is  $TS(G)$ . ( $G \simeq TS_1(G)$ )
- [Computer search] With respect to the number of vertices,  $C_7$  is the unique smallest planar graph  $G$  for which  $TS(G)$  is non-planar.
  - For each of 99 connected planar graphs  $G$  on 6 vertices,  $TS(G)$  is planar.
  - $TS_2(C_7)$  is non-planar.
- $TS_2(P_n)$  is planar for every  $n \geq 3$ .
  - $TS_2(P_n)$  is a subgraph of a  $n \times n$  grid.
- [Computer search]  $P_8$  is the largest path  $P$  for which  $TS(P)$  is planar.
  - $TS(P_8)$  is planar, and  $TS_3(P_9)$  is not.



4

# Graph Properties: $G$ vs. $TS_k(G)$ and $TS(G)$

Planar



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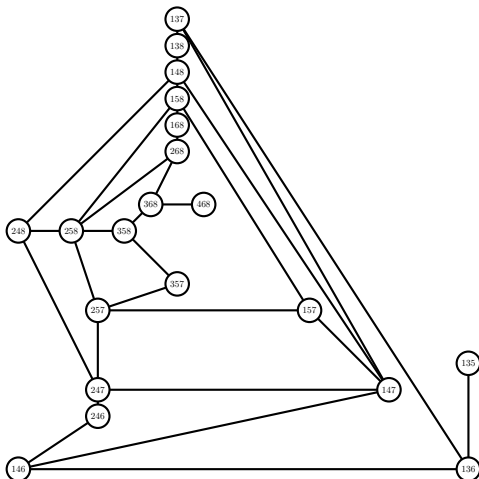
Realizing  
 $TS_k$ -Reconfiguration  
Graphs

Connected Split Graphs

Graph Properties:  $G$   
vs.  $TS_k(G)$  and  
 $TS(G)$

3

Planar  
Girth



**Figure:** A planar drawing of  $TS_3(P_8)$ . Each number of the form  $abc$  inside a node represents an independent set  $\{v_a, v_b, v_c\}$  of  $P_8 = v_1 \dots v_8$ .

4

# Graph Properties: $G$ vs. $TS_k(G)$ and $TS(G)$

Planar



Avis and Hoang

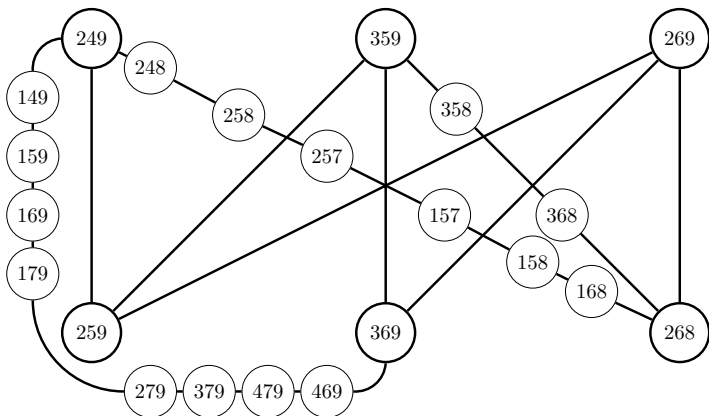
Realizing  
 $TS_k$ -Reconfiguration  
Graphs

Connected Split Graphs

Graph Properties:  $G$   
vs.  $TS_k(G)$  and  
 $TS(G)$

3

Planar  
Girth



**Figure:** A subdivision of  $K_{3,3}$  that is contained in  $TS_3(P_9)$ . Each number of the form  $abc$  inside a node represents an independent set  $\{v_a, v_b, v_c\}$  of  $P_9 = v_1 \dots v_9$ .

4

# Graph Properties: $G$ vs. $TS_k(G)$ and $TS(G)$

Girth



The *girth* of a graph  $G$  is the smallest size of a cycle in  $G$ , and is  $\infty$  if  $G$  is acyclic.

## Girth

- $\text{girth}(TS(P_n))$  is 4 for every  $n \geq 5$  and  $\infty$  otherwise.
  - $TS(P_n)$  has a  $C_4$  when  $n \geq 5$ . Moreover, since  $P_n$  is bipartite, so is  $TS(P_n)$ , i.e., it does not contain a  $C_3$ .

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 $TS(G)$

Planar  
Girth

4

4

# Graph Properties: $G$ vs. $TS_k(G)$ and $TS(G)$

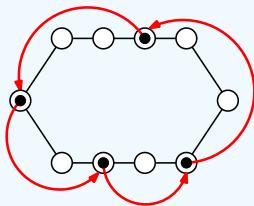
Girth



The **girth** of a graph  $G$  is the smallest size of a cycle in  $G$ , and is  $\infty$  if  $G$  is acyclic.

## Girth

- $\text{girth}(TS(P_n))$  is 4 for every  $n \geq 5$  and  $\infty$  otherwise.
  - $TS(P_n)$  has a  $C_4$  when  $n \geq 5$ . Moreover, since  $P_n$  is bipartite, so is  $TS(P_n)$ , i.e., it does not contain a  $C_3$ .
- For  $1 \leq k < n/2$ ,  $\text{girth}(TS_k(C_n)) = n$ . If  $k = n/2$ , we have  $\text{girth}(TS_k(C_n)) = \infty$ .
  - Let  $I \in TS_k(G)$ . How to form a cycle in  $TS_k(C_n)$  containing  $I$ ?



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Planar

Girth

4

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