# **AFSA**

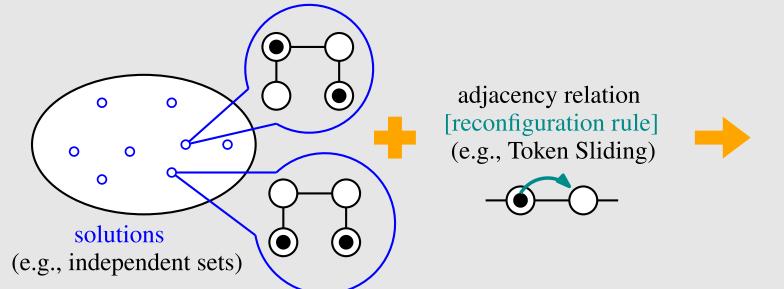
## The Application of Forbidden Structures in Solving Reconfiguration Problems

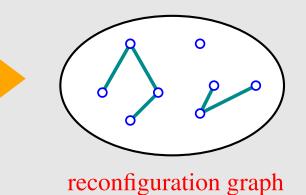
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#### **Reconfiguration Problems**

... study the relationship between *solutions* of a given *source problem* (e.g., Satisfiability, INDEPENDENT SET, VERTEX COVER, VERTEX-COLORING, etc.).





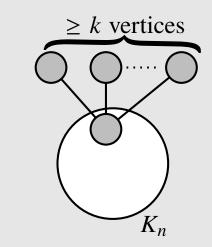
#### Figure 1. Reconfiguration.

Some typical questions:

- REACHABILITY: Is there a *path* between two given solutions?
- SHORTEST TRANSFORMATION: If REACHABILITY is yes, can we find a *shortest path*?

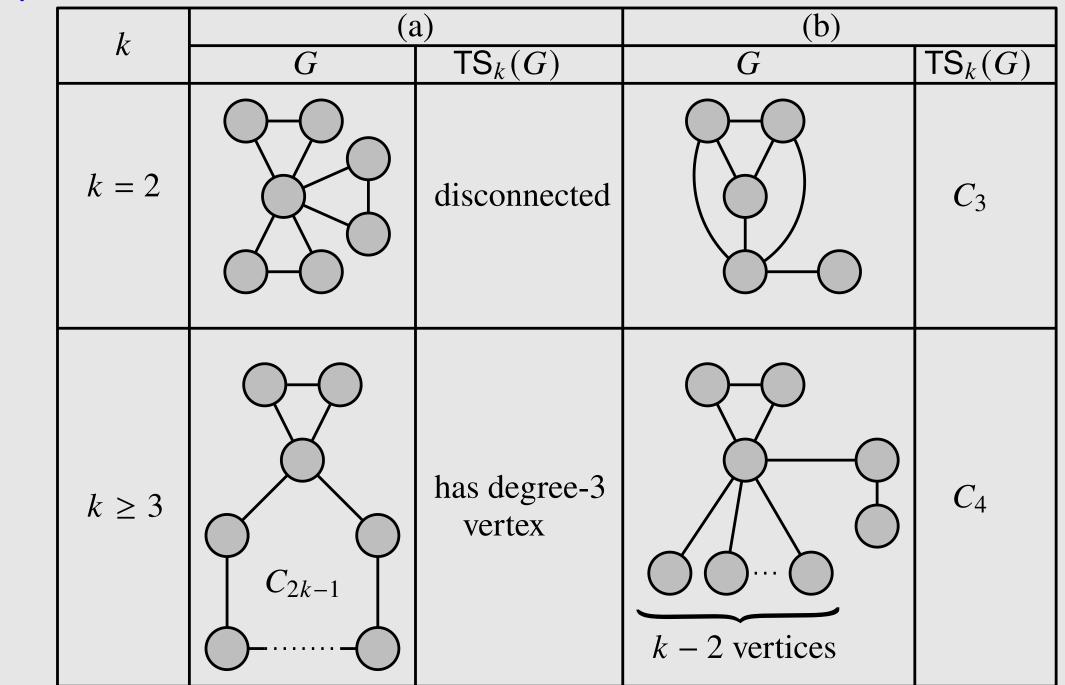
### Find G s.t. $TS_k(G)$ ( $k \ge 2$ ) Has Certain Properties [Avis and Hoang 2022]

■ *Cliques*. (*G* contains  $K_n \Leftrightarrow \mathsf{TS}(G)$  contains  $K_n$ .) There is *G* s.t. *G* has a  $K_n$  and  $\mathsf{TS}_k(G)$  ( $k \ge 2$ ) doesn't. *Design G s.t. exactly one token moves inside a clique*.



#### Figure 6. A desired graph G.

■ Eulerianity.

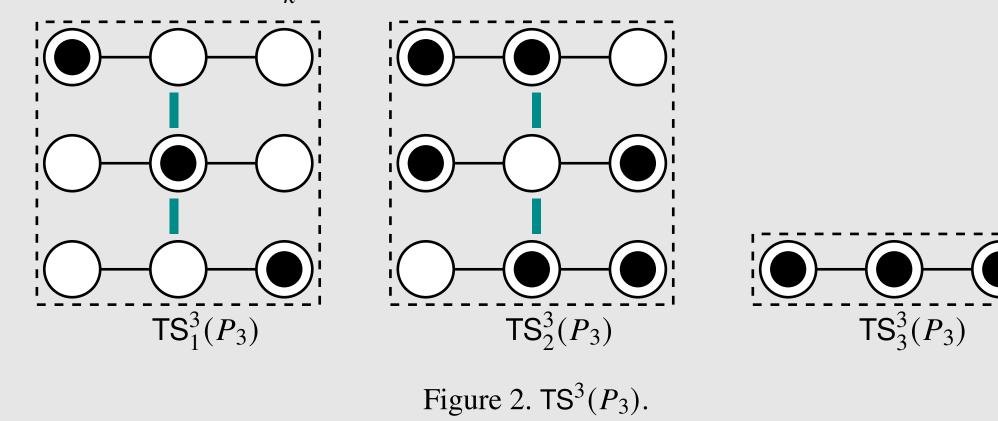




CONNECTIVITY: Is there a *path* between *any* two given solutions?
DIAMETER: Is the *maximum distance* between any two solutions bounded?
and so on.

#### **Example Problem: Reconfiguration of** *p***-PATH VERTEX COVER**

- Source Problem: *p*-PATH VERTEX COVER ( $p \ge 2$ ).
  - **Input:** G = (V, E), k.
  - Question: Is there a *p*-path vertex cover (*p*-PVC) of G, i.e., a vertex-subset I s.t. every path on p vertices in G contains at least one vertex from I, of size at most k?
  - A 2-PVC I is also called a *vertex cover* and  $V \setminus I$  is an *independent set*.
- Adjacency Relation: Token Sliding (TS).
- Two *p*-PVCs *I*, *J* are *adjacent* if there exist  $u, v \in V$  s.t.  $I \setminus J = \{u\}, J \setminus I = \{v\}$ , and  $uv \in E$ .
- **Reconfiguration Graph:**  $TS_k^p(G)$  and  $TS^p(G)$ .



**Note:** Reconfiguration graphs for VERTEX COVER and INDEPENDENT SET are the same. When p = 2, since several known results use INDEPENDENT SET as the source problem, we use it instead of VERTEX COVER, and use  $\mathsf{TS}_k(G)$  and  $\mathsf{TS}(G)$  to indicate  $\mathsf{TS}_k^2(G)$  and  $\mathsf{TS}^2(G)$ , respectively.

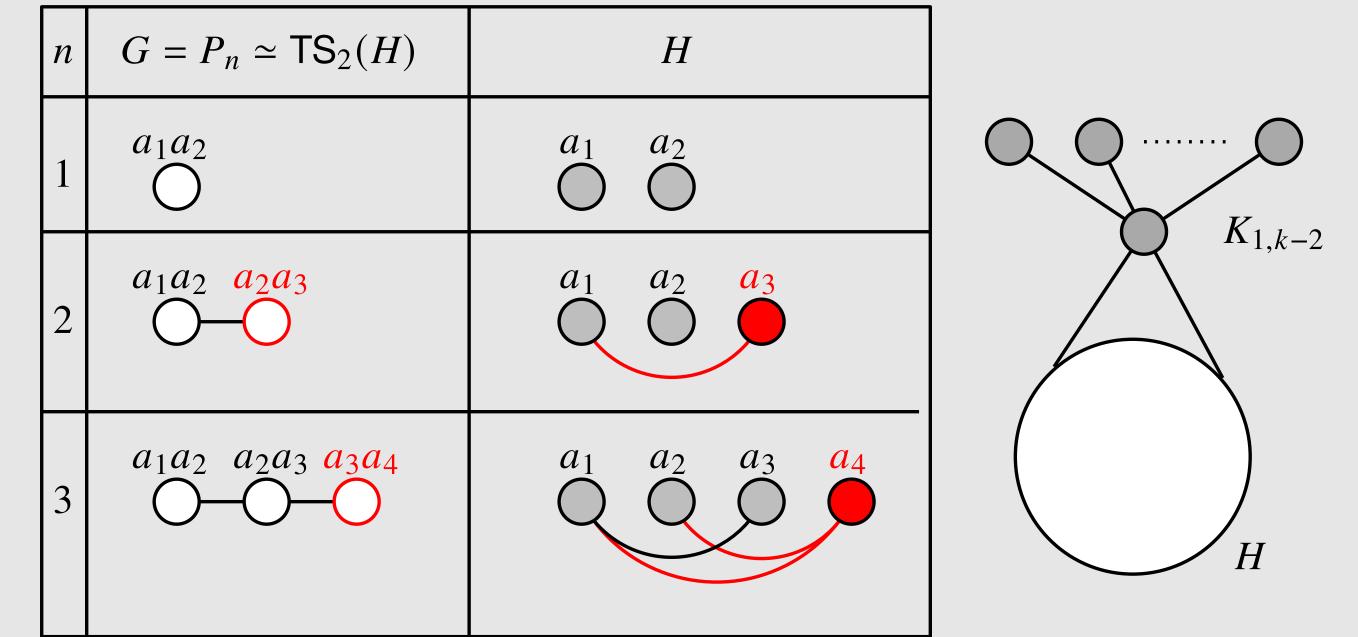
Figure 7. (a) *G* is Eulerian and  $\mathsf{TS}_k(G)$  isn't. (b) *G* isn't Eulerian and  $\mathsf{TS}_k(G)$  is.

Design G s.t. some special token has exactly one way to move.

**Future Goal:** More graph properties?

#### Find *H* s.t. $TS_k(H) \simeq G$ ( $k \ge 2$ ) for some graph *G* [Avis and Hoang 2022]

- $G = P_n$  and k = 2: Design H s.t. once a token is on  $a_{n+1}$ , the only choice for placing the other is on  $a_n$ .  $(V(H) = \{a_1, \dots, a_n, a_{n+1}\}.)$
- Generalize for fixed  $k \ge 3$ : Join every vertex of  $H \simeq TS_2(P_n)$  to the center of a star  $K_{1,k-2}$ . Note that the k - 2 tokens on the star never move. (*H* has no size-3 independent set.)



#### **Forbidden Structures in Reconfiguration**

A *forbidden structure* is *part of a solution* S satisfying certain properties that *obstruct the existence of a path* in the reconfiguration graph between S and some other solution.
 Example: *rigid tokens* (= tokens that never move) in each node of TS<sub>k</sub>(G).

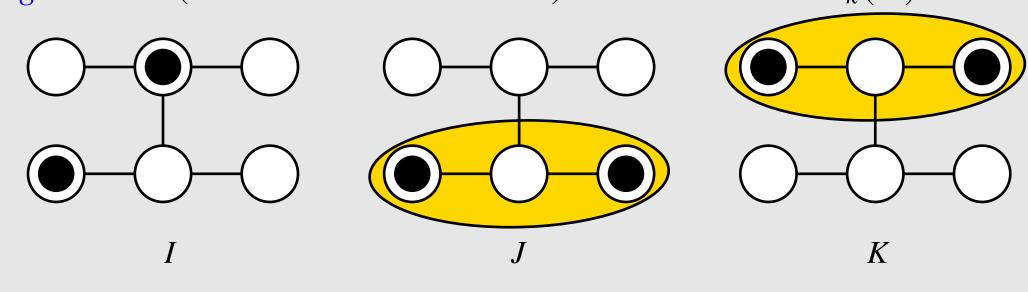


Figure 3. Independent sets  $I, J, K \in TS_2(G)$  having no path connecting any two of them.

• Naturally, in  $TS^{p}(G)$ , forbidden structures involve tokens whose movements are "restricted".

#### **Reachability in** TS(G)

- Polynomial-time algorithms when G is a tree [Demaine et al. 2015], bipartite permutation graph [Fox-Epstein et al. 2015], or cactus graph [Hoang and Uehara 2016].
- **Open Problem:** *G* is *outerplanar*?

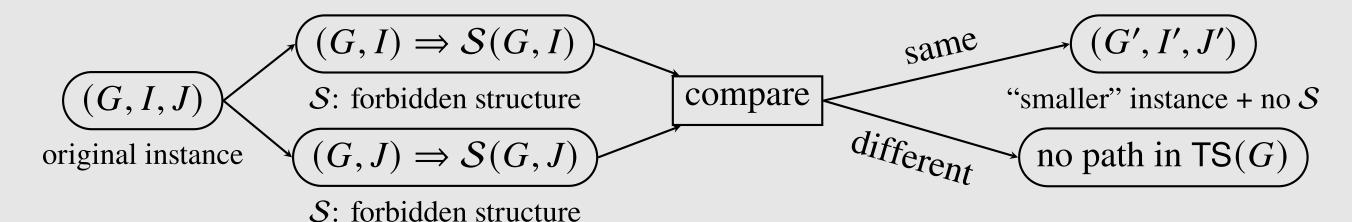


Figure 8. Design *H* s.t.  $\mathsf{TS}_k(H) \simeq G$   $(k \ge 2)$  where  $G = P_n$ .

■  $G = K_{1,n} (n \le k)$ . (If n > k, there is no H s.t.  $\mathsf{TS}_k(H) \simeq K_{1,n}$ .) Design H s.t. each token on  $a_i$   $(1 \le i \le k)$  either moves back-and-forth along an edge or never moves.

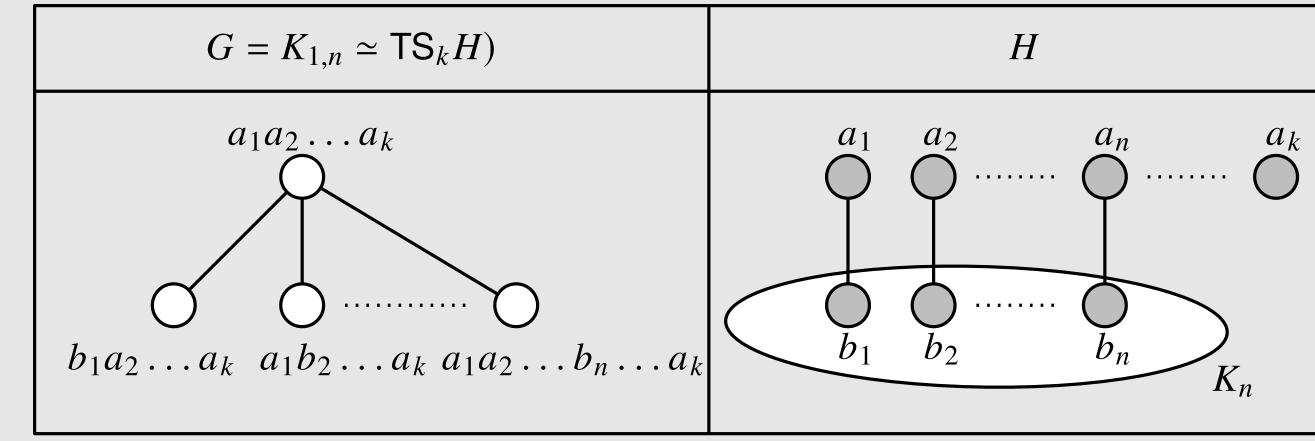


Figure 9. Design *H* s.t.  $\mathsf{TS}_k(H) \simeq G$   $(k \ge 2)$  where  $G = K_{1,n}$   $(n \le k)$ .

#### ■ **Open Problem:** *G* is a *tree*?

■ If there exists *H* s.t.  $TS_2(H) \simeq G$  for a tree *G*, *H* does not contain any *P*<sub>5</sub> as an induced subgraph.

Figure 4. A general approach to solve REACHABILITY using forbidden structures.

#### **REACHABILITY in** $TS^p(G)$ ( $p \ge 3$ )

■ PSPACE-*hardness* when G is *planar*  $\cap$  *maximum degree* 3 [Hoang, Suzuki, and Yagita 2020].

- AND/OR NCL graph.
- **Blue** edge  $\Rightarrow$  weight 2.
- Red edge ⇒ weight 1.
   Total in-weight ≥ 2.
- Reverse edge-direction.
- Each dashed rectangle represents a connecting part.
- Design gadgets s.t. no token ever leaves its connecting part.
- **Open Problem:** *G* is *bipartite*?

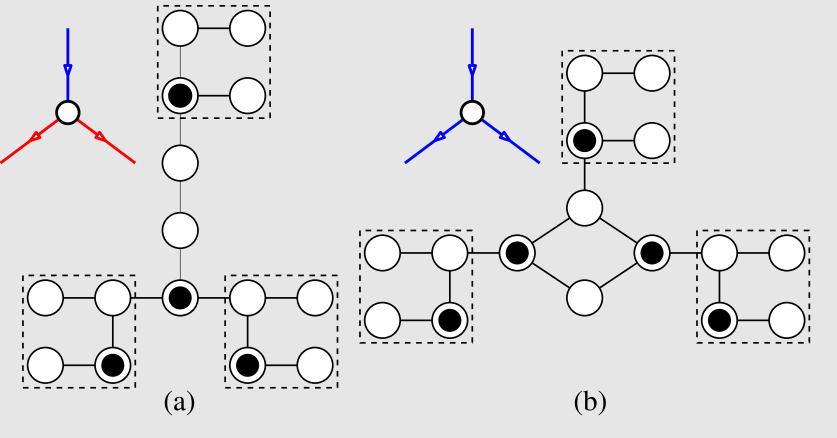


Figure 5. Gadgets when p = 3. (a) AND gadget. (b) OR gadget.

#### References

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